

Distributed Systems

22. Clusters

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Computer System Design

Highly Available Systems

- Incorporate elements of fault-tolerant design
 - Replication, TMR
- Fully fault tolerant system will offer non-stop availability
 - But you can't achieve this!

Problem:

- \uparrow in availability $\Rightarrow \uparrow$ \$\$

Highly Scalable Systems

- SMP architecture

Problem:

Performance gain as $f(\# \text{ processors})$ is sublinear

- Contention for resources (bus, memory, devices)
- Also ... the solution is expensive!

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Clustering

Achieve reliability and scalability by interconnecting multiple independent systems

Cluster:

A group of standard, autonomous servers configured so they appear on the network as a single machine

Single system image

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Ideally...

- Bunch of off-the shelf machines
- Interconnected on a high speed LAN
- Appear as one system to users
- Processes are load-balanced across the cluster
 - May migrate
 - May run on different systems
 - All IPC mechanisms and file access available
- Fault tolerant
 - Components may fail
 - Machines may be taken down

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We don't get all that (yet)

... at least not in one general purpose package

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Clustering types

- Supercomputing (HPC)
 - and Batch processing
- High availability (HA)
- Load balancing
- Storage

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Cluster Components

Cluster Components

- Cluster membership
- Quorum
- Configuration & service management
- Interconnect
- Storage
- Heartbeat & heartbeat network

Cluster membership

- Software to manage **cluster membership**
 - What are the nodes in the cluster?
 - Which nodes in the cluster are currently *alive* (active)?
- We saw this:
 - Group Membership Service in virtual synchrony
 - GFS master, HDFS Namenode
 - Bigtable master
 - Pregel master
 - MapReduce & Spark masters

Quorum

- Some members may be dead or disconnected
- **Quorum**
 - Number of elements that must be online for the cluster to function
 - Voting algorithm to determine whether the set of nodes has quorum (a majority of nodes to keep running)
- Keeping track of quorum
 - Count cluster nodes running the cluster manager
 - If over $\frac{1}{2}$ are active, the cluster has quorum
 - Forcing a majority avoids **split-brain**
- We saw this with Paxos & Raft

Cluster configuration & service management

- **Cluster configuration system**
 - Manages configuration of systems and software in a cluster
 - Runs in each cluster node
 - Changes propagate to all nodes
 - Administrator has a single point of control
- **Service management**
 - Identify which applications run where
 - Specify how failover occurs
 - **Active**: system runs a service
 - **Standby**: Which system(s) can run the service if the active dies
 - E.g., Map-Reduce, Pregel, Spark all use coordinators

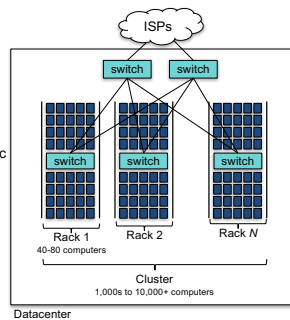
Interconnect

Cluster Interconnect

- Provide communication between nodes in a cluster

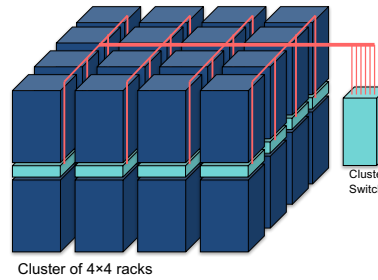
Goals

- **Low latency**
 - Avoid OS overhead, layers of protocols, retransmission, etc.
- **High bandwidth**
 - High bandwidth, switched links
 - Avoid overhead of sharing traffic with non-cluster data
- **Low CPU overhead**
- **Low cost**
 - Cost usually matters if you're connecting thousands of machines
- Usually a LAN is used: best **\$/performance** ratio



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Cluster Interconnect



Assume:
10 Gbps per server
40 servers per rack
⇒ 400 Gbps/rack

16 racks
⇒ 8 Tbps

Max switch capacity
currently ~ 5 Tbps
⇒ Need at least two
cluster switches

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Switches add latency

- Within one rack
 - One **switch latency** $\approx <1...8 \mu s$ for a 10 Gbps switch
 - Two links (to switch + from switch) @ 1-2 meters of cable
 - **Propagation time** in copper $\approx 2 \times 10^8 \text{ m/s} \approx 5 \text{ ns/m}$
- Between racks in a cluster
 - Three switch latency ($\approx <3...24 \mu s$)
 - 4 links (to rack switch + to cluster switch + back to target rack)
 - ~10-100 meters distance (50 ... 500 ns)
- Plus the normal latency of sending & receiving packets:
 - System latency of processing the packet, OS mode switch, queuing the packet, copying data to the transceiver, ...
 - **Serialization delay** = time to copy packet to media $\approx 1 \mu s$ for a 1KB packet on a 10 Gbps link

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Dedicated cluster interconnects

- **TCP adds latency**
 - Operating system overhead, queueing, checksums, acknowledgements, congestion control, fragmentation & reassembly, ...
 - Lots of interrupts
 - Consumes time & CPU resources
- **How about a high-speed LAN without the overhead?**
 - LAN dedicated for intra-cluster communication
 - Sometimes known as a **System Area Network (SAN)**
 - Dedicated network for storage: **Storage Area Network (SAN)**

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Example High-Speed Interconnects

Common traits

- **TCP/IP Offload Engines (TOE)** – TCP stack at the switch
- **Remote Direct Memory Access (RDMA)** – memory copy with no CPU involvement
- **Intel I/O Acceleration Technology (IOAT)** – combines TOE & RDMA – data copy without CPU, TCP packet coalescing, low-latency interrupts, ...

Example: InfiniBand

- Switch-based point-to-point bidirectional serial links
- Link processors, I/O devices, and storage
- Each link has one device connected to it
- Enables data movement via **remote direct memory access (RDMA)**
 - No CPU involvement!
- Up to 25 Gbps/link
 - Links can be aggregated: up to 300 Gbps with 12x aggregate

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Example High-Speed Interconnects

- **Myricom's Myrinet**
 - 10 Gbps Ethernet
 - PCI Express x8 connectivity
 - Low-latency, high-bandwidth, interprocess communication between nodes
 - Firmware offloads TCP functionality onto the card
 - Aggregate bandwidth of ~19.8 Gb/s
 - Example: used in IBM's Linux Cluster Solution
- **IEEE 802.1 Data Center Bridging (DCB)**
 - Set of standards that extend Ethernet
 - Lossless data center transport layer
 - Priority-based flow control, congestion notification, bandwidth management

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Disks

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Shared storage access

- If an application can run on any machine, how does it access file data?
- If an application fails over from one machine to another, how does it access its file data?
- Can applications on different machines share files?

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Network (Distributed) File Systems

One option:

- Network file systems: NFS, SMB, AFS, AFP, etc.
- Works great for many applications

Concerns

- Availability
 - Address with replication (most file systems offer little)
- Performance
 - Remote systems on a LAN vs. local bus access
 - Overhead of remote operating system & network stack
 - Point of congestion
 - Look at GFS/HDFS to distribute file data across lots of servers ... or other parallel file systems, such as Lustre, GlusterFS, or Ceph

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Shared disks & Cluster file systems

- Shared disk
 - Allows multiple systems to share access to disk drives
 - Works well if there isn't much contention
- **Cluster File System**
 - Client runs a file system accessing a shared disk at the **block level**
 - *vs. a distributed file system, which access at a file-system level*
 - No client/server roles, no disconnected modes
 - All nodes are peers and access a shared disk(s)
 - **Distributed Lock Manager (DLM)**
 - Process to ensure mutual exclusion for disk access
 - Provides inode-based locking and caching control
 - Not needed for local file systems on a shared disk

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Cluster File Systems

- Examples:
 - IBM General Parallel File System (GPFS)
 - Microsoft Cluster Shared Volumes (CSV)
 - Oracle Cluster File System (OCFS)
 - Red Hat Global File System (GFS2)
- Linux GFS2 (no relation to Google GFS)
 - Cluster file system accessing storage at a **block level**
 - **Cluster Logical Volume Manager (CLVM)**: volume management of cluster storage
 - **Global Network Block Device (GNBD)**: block level storage access over ethernet: cheap way to access block-level storage

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The alternative: shared nothing

Shared nothing

- No shared devices
- Each system has its own storage resources
- No need to deal with DLMs
- If a machine A needs resources on B, A sends a message to B
 - If B fails, storage requests have to be switched over to a live node
- **Need exclusive access to shared storage**
 - Multiple nodes may have access to shared storage
 - Only one node is granted exclusive access at a time – *one owner*
 - Exclusive access changed on failover

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SAN: Computer-Disk interconnect

- Storage Area Network (SAN)
- Separate network between nodes and storage arrays
 - Fibre channel
 - iSCSI
- Any node can be configured to access any storage through a fibre channel switch
- Acronyms
 - **DAS**: Direct Attached Storage
 - **SAN**: block-level access to a disk via a network
 - **NAS**: file-level access to a remote file system (NFS, SMB,...)

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Failover

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HA issues

- How do you detect failover?
- How long does it take to detect?
- How does a dead application move/restart?
- Where does it move to?

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Heartbeat network

- Machines need to detect faulty systems
 - **Heartbeat**: Periodic “ping” mechanism
 - An “are you alive” message
- Need to distinguish **system faults** from **network faults**
 - Useful to maintain redundant networks
 - Avoid split-brain issues in systems without quorum (e.g., a 2-node cluster)
- Once you know who is dead or alive, then determine a course of action

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Failover Configuration Models

- **Active/Passive**
 - Requests go to active system
 - Passive nodes do nothing until they’re needed
 - Passive nodes maintain replicated state (e.g., SMR/Virtual Synchrony)
 - Example: Chubby
- **Active/Active**
 - Any node can handle a request
 - Failed workload goes to remaining nodes
 - Replication must be N -way for N active nodes
- **Active/Passive: $N+M$**
 - M dedicated failover node(s) for N active nodes

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Design options for failover

- **Cold failover**
 - Application restart
 - Example: *map and reduce workers in MapReduce*
- **Warm failover**
 - Restart last checkpointed image
 - Relies on application checkpointing itself periodically
 - Example: *Pregel*
- **Hot failover**
 - Application state is synchronized across systems
 - E.g., replicated state machines or lockstep synchronization at the CPU level
 - Spare is ready to run immediately
 - May be difficult at a fine granularity, prone to software faults (e.g., what if a specific set of inputs caused the software to die?)
 - Example: *Chubby*

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Design options for failover

- With either type of failover ...
- **Multi-directional failover**
 - Failed applications migrate to / restart on available systems
- **Cascading failover**
 - If the backup system fails, application can be restarted on another surviving system

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IP Address Takeover (IPAT)

Depending on the deployment:

- **Ignore**
 - IP addresses of services don't matter. A load balancer, name server, or coordinator will identify the correct machine
- **Take over IP address**
 - A node in an active/passive configuration may need to take over the IP address of a failed node
- **Take over MAC address**
 - MAC address takeover may be needed if we cannot guarantee that other nodes will flush their ARP cache
- **Listen on multiple addresses**
 - A node in an active/active configuration may need to listen on multiple IP addresses

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Hardware support for High Availability

- **Hot-pluggable components**
 - Minimize downtime for component swapping
 - E.g., disks, power supplies, CPU/memory boards
- **Redundant devices**
 - Redundant power supplies
 - Parity on memory
 - Mirroring on disks (or RAID for HA)
 - Switchover of failed components
- **Diagnostics**
 - On-line identification & service

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Fencing

- **Fencing**: method of isolating a node from a cluster
 - Apply to failed node
 - Disconnect I/O to ensure data integrity
 - Avoid problems with Byzantine failures
 - Avoids problems with *fail-restart*
 - Restarted node has not kept up to date with state changes
- **Types of fencing**
 - **Power fencing**: shut power off a node
 - **SAN fencing**: disable a Fibre Channel port to a node
 - Disable access to a global network block device (GNBD) server
 - Software fencing: remove server processes from the group
 - E.g., virtual synchrony

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Cluster software hierarchy

Example: Windows Server cluster abstractions

Top tier: Cluster abstractions

- Failover manager (what needs to be started/restarted?)
- Resource monitor (what's going on?)
- Cluster registry (who belongs in the cluster?)

Middle tier: Distributed operations

- Global status update
- Membership
- Quorum (leader election)

Bottom tier: OS and drivers

- Cluster disk driver, cluster network drivers
- IP address takeover

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High Performance Computing (HPC)

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Supercomputers

- Most powerful supercomputer: 94 petaflops
 - **Sunway TaihuLight** – *National Supercomputing Center in Wuxi, China*
 - 40,960 1.45 GHz SW26010 64-bit RISC processors
 - Each processor contains 260 processing cores
 - 40 cabinets
 - Interconnect built into the chip
 - Runs Linux (Raise)



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Titan Supercomputer: #5 on the list

- **Titan**, Oak Ridge National Laboratories
- Heterogeneous computing: GPUs + conventional CPUs
- 18,688 Cray XK6 compute nodes
 - Each node:
 - One AMD 16-core Opteron 6274 CPU @ 2.2 GHz
 - 32 GB DDR3 memory
 - Cray's Gemini network
 - 18,688 nodes are augmented with:
 - NVIDIA Tesla Kepler K20 GPU application processor
 - K20 has 2,688 CUDA cores (7.1 billion transistors per GPU)
- Peak performance: > 20 petaFLOPS (10¹⁵ FLOPS)

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Titan

- OS
 - Cray Linux Environment (based on SUSE 11)
 - Some cores are dedicated to OS tasks so that apps on other cores are not interrupted by the OS
 - Batch job scheduling (Moab and Torque)
- Total:
 - 299,008 AMD Opteron CPU cores
 - 710 TB total system memory
 - Connected to a 240 GB/s Spider file system with 10 petabytes
 - 10,000 1TB 7200rpm 2.5" hard drives
 - Total transistor count: 177 trillion!
 - Total power consumption: 7 (typical) - 9 megawatts (peak)

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- Supercomputers are *not* distributed computers
- Lots of processors connected by high-speed networks
- Shared memory access
- Shared operating system (all TOP500 run Linux)

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Supercomputing clusters

- Supercomputing cluster
 - Build a supercomputer from commodity computers & networks
 - A distributed system
- Target complex, typically scientific, applications:
 - Large amounts of data
 - Lots of computation
 - Parallelizable application
- Many custom efforts
 - Typically Linux + message passing software + remote exec + remote monitoring



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Programming tools: MPI

MPI: Message Passing Interface

- API for sending/receiving messages
 - Optimizations for shared memory & NUMA
 - Group communication support
- Other features:
 - Scalable file I/O
 - Dynamic process management
 - Synchronization (barriers)
 - Combining results

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Programming tools: PVM

- **PVM**: Parallel Virtual Machine
- Software that emulates a general-purpose heterogeneous computing framework on interconnected computers
- Model: app = set of tasks
 - **Functional parallelism**: tasks based on function: input, solve, output
 - **Data parallelism**: tasks are the same but work on different data
- PVM presents library interfaces to:
 - Create tasks
 - Use global task IDs
 - Manage groups of tasks
 - Pass basic messages between tasks

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Clustering for performance

- Example: Early (>20 years old!) effort on Linux – Beowulf
 - Initially built to address problems associated with large data sets in Earth and Space Science applications
 - From Center of Excellence in Space Data & Information Sciences (CESDIS)
 - Division of University Space Research Association at the Goddard Space Flight Center
 - Still used!
- This isn't one fixed package
 - Just an example of putting tools together to create a supercomputer from commodity hardware

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What makes it possible?

- Commodity off-the-shelf computers are cost effective
- Publicly available software:
 - Linux, GNU compilers & tools
 - MPI (message passing interface)
 - PVM (parallel virtual machine)
- Low cost, high speed networking
- Experience with parallel software
 - Difficult: solutions tend to be custom

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What can you run?

- Programs that do not require fine-grain communication
- Basic properties
 - Nodes are dedicated to the cluster
 - Performance of nodes not subject to external factors
 - Interconnect network isolated from external network
 - Network load is determined only by application
 - Global process ID provided
 - Global signaling mechanism

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Beowulf configuration

Includes:

- **BProc: Beowulf distributed process space**
 - Start processes on other machines
 - Global process ID, global signaling
- **Network device drivers**
 - Channel bonding, scalable I/O
- **File system (file sharing is generally not critical)**
 - NFS root
 - unsynchronized
 - synchronized periodically via rsync

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Beowulf programming tools

- PVM and MPI libraries
- Distributed shared memory
 - Page based: software-enforced ownership and consistency policy
- Cluster monitor
- Global *ps*, *top*, *uptime* tools
- Process management
 - Batch system
 - Write software to control synchronization and load balancing with MPI and/or PVM
 - Job scheduling: use something like HTCondor or Mosix

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Another example

- **Rocks Cluster Distribution**
 - Employed on over 1,300 clusters
 - Mass installation is a core part of the system
 - Mass re-installation for application-specific configurations
 - Front-end central server + compute & storage nodes
 - Based on CentOS Linux
 - Rolls: collection of packages
 - Base roll includes: PBS (portable batch system), PVM (parallel virtual machine), MPI (message passing interface), job launchers, ...

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Another example: Microsoft HPC Pack

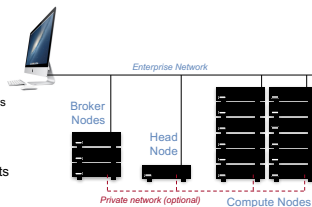
- Clustering package for Windows & Windows Server
 - Supports on-premises & on-demand computers deployed in Azure
- **Systems Management**
 - Management Console: plug-in to System Center UI with support for Windows PowerShell
 - RIS (Remote Installation Service)
- **Networking**
 - MS-MPI (Message Passing Interface)
 - ICS (Internet Connection Sharing) : NAT for cluster nodes
 - Network Direct RDMA (Remote DMA)
- **Job scheduler**
- **Storage:** iSCSI SAN and SMB support
- **Failover support**

See <http://www.microsoft.com/hpc/en-us/product/cluster-computing.aspx>

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Microsoft HPC Pack

- **Head node**
 - Cluster management
 - Provides failover
 - Mediates access to cluster
 - Job scheduler
 - Queues jobs
 - Initiates tasks on compute nodes
 - Monitors status of jobs & nodes
- **Broker nodes**
 - Load balances service requests
 - Return results to client
- **Compute nodes**
 - Carry out work assigned by job scheduler



See <http://www.microsoft.com/hpc/en-us/product/cluster-computing.aspx>

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Batch Processing

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Batch processing

- **Non-interactive processes**
 - Schedule, run eventually, collect output
- **Examples:**
 - MapReduce, many supercomputing tasks (circuit simulation, climate simulation, physics simulation)
 - Graphics rendering
 - Maintain a queue of frames to be rendered
 - Have a dispatcher to remotely exec process
- In many cases – minimal or no IPC needed
- Coordinator dispatches jobs

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Single-queue work distribution: Render Farms

- **Examples:**
 - **Pixar:**
 - 12,500 cores on Dell render blades running Linux and Renderman
 - Custom Linux software for articulating, animating/lighting (Marionette), scheduling (Ringmaster), and rendering (RenderMan)
 - Average time to render a single frame
 - Cars (2006): 8 hours
 - Cars 2 (2011): 11.5 hours
 - Monsters University (2013): 29 hours
 - 100 million CPU hours for the whole movie!
 - **DreamWorks:**
 - Thousands of HP Z820 workstations
 - 32-96 GB RAM, 160 TB SSD boot drive + 500 GB data drive, Nvidia Quadro 5000 (352 cores)
 - Movie file may use 250 TB for storage
 - Kung Fu Panda 2 used 100 TB data and required over 55 million render hours
 - Shrek 3: 20 million CPU render hours. Platform LSF used for scheduling + Maya for modeling + Avid for editing+ Python for pipelining – movie uses 24 TB storage

<http://venturebeat.com/2013/04/24/the-making-of-pixars-latest-technological-marvel-monsters-university-2/>
http://news.cnet.com/8301-13772_3-20088109-62/new-technology-reve-up-pixars-cars-2/

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Single-queue work distribution: Render Farms

- Disney Animation's render farm (2014)
 - Hardware
 - Spread across four sites
 - Over 55,000 Intel cores
 - 500 TB memory
 - Uses about 1.5 MW of power
 - Linked with 10 Gb Ethernet
 - All non-volatile storage is SSD
 - In-house CODA job distribution system
 - Typically performs 1.1 million render hours per day (hundreds of thousands of tasks)

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Batch Processing

- OpenPBS.org:
 - Portable Batch System
 - Developed by Veridian MRJ for NASA
- Commands
 - *Submit job scripts*
 - Submit interactive jobs
 - Force a job to run
 - *List jobs*
 - *Delete jobs*
 - *Hold jobs*

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Load Balancing

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Functions of a load balancer

- Load balancing
- Failover
- Planned outage management

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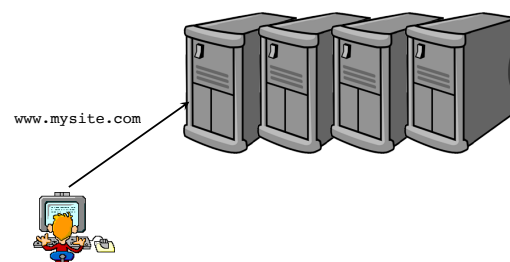
Redirection

Simplest technique
HTTP REDIRECT error code

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Redirection

Simplest technique
HTTP REDIRECT error code

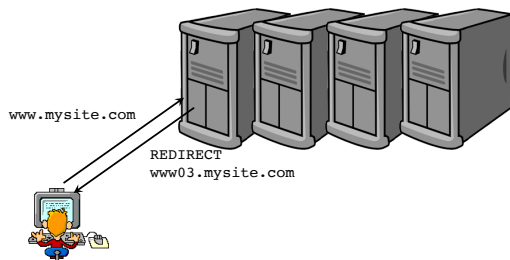


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Redirection

Simplest technique

HTTP REDIRECT error code

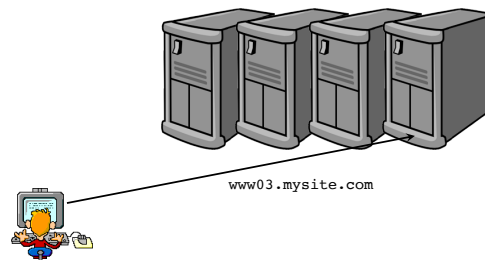


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Redirection

Simplest technique

HTTP REDIRECT error code



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Redirection

- Trivial to implement
- Successive requests automatically go to the same web server
 - Important for sessions
- Visible to customer
 - Don't like the changing URL
- Bookmarks will usually tag a specific site

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Load balancing router

As routers got smarter

- Not just simple packet forwarding
- Most support packet filtering
- Add load balancing to the mix
- This includes most IOS-based Cisco routers, Altheon, F5 Big-IP

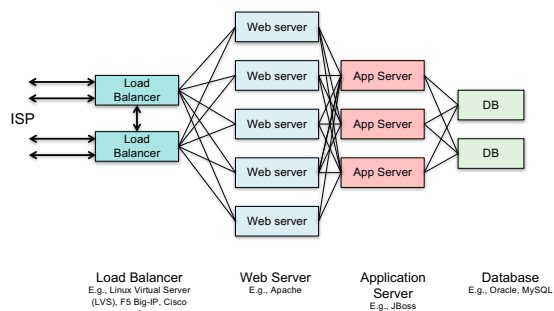
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Load balancing router

- Assign one or more virtual addresses to physical address
 - Incoming request gets mapped to physical address
- Special assignments can be made per port
 - e.g., all FTP traffic goes to one machine
- **Balancing decisions:**
 - Pick machine with least # TCP connections
 - Factor in weights when selecting machines
 - Pick machines round-robin
 - Pick fastest connecting machine (SYN/ACK time)
- **Persistence**
 - Send all requests from one user session to the same system

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Load Balancing



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DNS-based load balancing

- Round-Robin DNS
 - Respond to DNS requests with a list of addresses instead of one
 - The order of the list is permuted with each response
- Geographic-based DNS response
 - Multiple clusters distributed around the world
 - Balance requests among clusters
 - Favor geographic proximity
 - Examples:
 - BIND with Geodns patch
 - PowerDNS with geobackend
 - Amazon Route 53



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The end

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